

Mathematics for Intelligent Systems

Lecture 10 Homework

(Optimization)

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1 Convergence proof

a) Given a function $f : \mathbb{R}^n \rightarrow \mathbb{R}$ with $f_{\min} = \min_x f(x)$. Assume that its Hessian—that is, the eigenvalues of $\nabla^2 f$ —are lower bounded by $m > 0$ and upper bounded by $M > m$. Prove that for any $x \in \mathbb{R}^n$ it holds

$$f(x) - \frac{1}{2m} |\nabla f(x)|^2 \leq f_{\min} \leq f(x) - \frac{1}{2M} |\nabla f(x)|^2 .$$

Tip: Start with bounding the 2nd-order Taylor expansion. Then consider the minima of these bounds. Note, it also follows:

$$|\nabla f(x)|^2 \geq 2m(f(x) - f_{\min}) .$$

b) Consider backtracking line search with Wolfe parameter $\rho_{1s} \leq \frac{1}{2}$, and step decrease factor ρ_{α}^- . First prove that line search terminates the latest when $\frac{\rho_{\alpha}^-}{M} \leq \alpha \leq \frac{1}{M}$, and then it found a new point y for which

$$f(y) \leq f(x) - \frac{\rho_{1s} \rho_{\alpha}^-}{M} |\nabla f(x)|^2 .$$

From this, using the result from a), prove the convergence equation

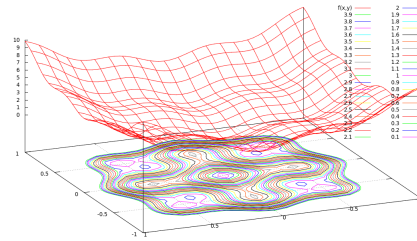
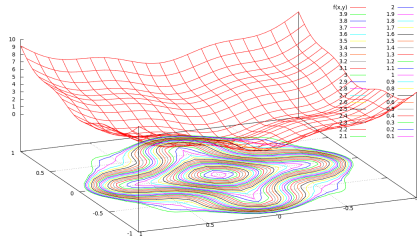
$$f(y) - f_{\min} \leq \left[1 - \frac{2m \rho_{1s} \rho_{\alpha}^-}{M} \right] (f(x) - f_{\min}) .$$

2 Misc

The Gauss-Newton method uses the “approximate Hessian” $2\nabla\phi(x)^\top \nabla\phi(x)$. First show that for any vector $v \in \mathbb{R}^n$ the matrix vv^\top is symmetric and semi-positive-definite.¹ From this, how can you argue that $\nabla\phi(x)^\top \nabla\phi(x)$ is also symmetric and semi-positive-definite?

¹ A matrix $A \in \mathbb{R}^{n \times n}$ is semi-positive-definite simply when for any $x \in \mathbb{R}^n$ it holds $x^\top Ax \geq 0$. Intuitively: A might be a metric as it “measures” the norm of any x as positive. Or: If A is a Hessian, the function is (locally) convex.

3 Gauss-Newton



In $x \in \mathbb{R}^2$ consider the function

$$f(x) = \phi(x)^\top \phi(x), \phi(x) = \begin{pmatrix} \sin(ax_1) \\ \sin(ax_2) \\ 2x_1 \\ 2cx_2 \end{pmatrix}$$

The function is plotted above for $a = 4$ (left) and $a = 5$ (right, having local minima), and conditioning $c = 1$. The function is non-convex.

Extend your backtracking method implemented in the last week's exercise to a Gauss-Newton method (with constant λ) to solve the unconstrained minimization problem $\min_x f(x)$ for a random start point in $x \in [-1, 1]^2$. Compare the algorithm for $a = 4$ and $a = 5$ and conditioning $c = 3$ with gradient descent.